

First, in order for \bar{i}_L to be well-defined the linear system $|L|$ can not have any base points, i.e., for each $x \in M$ the restriction map

$$H^0(M, \mathcal{O}(L)) \xrightarrow{r_x} L_x$$

must be surjective.

$$\begin{aligned} \Gamma \quad \bar{i}_L: M &\longrightarrow \mathbb{P}^N \\ x &\longmapsto [S_0(x), \dots, S_N(x)] \end{aligned}$$

base-point free $\Rightarrow \exists S_i(x) \neq 0 \Rightarrow r_x(S_i) = S_i(x) \neq 0$
 in $L_x \Rightarrow \{ \alpha S_i(x) \} = L_x \Rightarrow r_x$ is surjective. \rfloor

Granted this, \bar{i}_L will be an embedding if

1. \bar{i}_L is one to one. Clearly this is the case \Leftrightarrow for all x and y in M , there exists a section $s \in H^0(M, \mathcal{O}(L))$ vanishing at x but not at y , i.e. \Leftrightarrow the restriction map

$$(*) \quad H^0(M, \mathcal{O}(L)) \xrightarrow{r_{x,y}} L_x \otimes L_y$$

is surjective for all $x \neq y \in M$.

Γ (i) (\Leftarrow) . Clear (\Rightarrow) . $\bar{i}_L(x) \neq \bar{i}_L(y) \Leftrightarrow [S_0(x), \dots, S_N(x)] \neq [S_0(y), \dots, S_N(y)] \Rightarrow [S_0(x), S_1(x)] \neq [S_0(y), S_1(y)]$ say 0, 1. Suppose $S_0(x) = 0$. $S_0(y)$ must be non zero. If $S_1(x) = 0$, $S_1(y) \neq 0$. $S_0(x) \neq 0 \neq S_1(x)$.
 $\Rightarrow \exists \alpha, t \quad S_0(x) + \alpha S_1(x) = 0 \Rightarrow S_0(y) + \alpha S_1(y) \neq 0$.
 $\Rightarrow S_0 + \alpha S_1$ is a section satisfying the above condition.

(ii). $S_1(x) = 0$, $S_1(y) \neq 0$, & $S_2(x) \neq 0$, $S_2(y) = 0$.

Consider $S = S_1 + S_2 \Rightarrow S(x) = S_2(x) \neq 0$, $S(y) = S_1(y) \neq 0$.