

$$\begin{aligned} \Rightarrow \text{ Since } \partial \Lambda &= \sum_k e_k \partial_k \left(-\frac{i}{2} \sum_l \bar{e}_l e_l \right) \\ &= -\frac{i}{2} \sum_{k,l} \partial_k e_k \bar{e}_l e_l = -\frac{i}{2} \sum_{k,l} \partial_l e_l \bar{e}_k e_k, \\ \Lambda \partial &= \partial \Lambda - i \sum_k \partial_k \bar{e}_k. \end{aligned}$$

$$\begin{aligned} \cdot \bar{\partial}^* &= -\sum_k \partial_k \bar{e}_k \quad \Rightarrow \quad \Lambda \partial = \partial \Lambda + i \bar{\partial}^* \\ \Rightarrow [\Lambda, \partial] &= i \bar{\partial}^* \quad \text{so the identity is proved on } \mathbb{C}^n. \end{aligned}$$

To prove the result on a Kähler manifold M , we use the condition of osculation to show that the identity holds at any point: for $z_0 \in M$, we can choose a coframe $\varphi_1, \varphi_2, \dots, \varphi_n$ for the metric such that $d\varphi_i(z_0) = 0$.

The expression for Λ holds with dZ_I replaced by φ_I : we can make essentially the same computation for $[\Lambda, \bar{\partial}] \eta$ as on \mathbb{C}^n except that we will get terms involving $\bar{\partial} \varphi_i$. Since $[\Lambda, \bar{\partial}]$ involves only first derivatives, however, all the additional terms will have a factor $\bar{\partial} \varphi_i$ and hence will vanish at z_0 .

Likewise, we have computed $\partial^* \eta = C_n * \partial^* \eta$ on \mathbb{C}^n , where it agrees with $i [\Lambda, \bar{\partial}] \eta$: the computation on M in terms of the φ_i will again be the same except for additional terms involving $\bar{\partial} \varphi_i$, which vanish at z_0 . Thus we see that the identity holds at z_0 , hence everywhere.

This argument is just one instance of a general principle: any intrinsically defined identity that involves the metric together with its first derivatives and which is valid on \mathbb{C}^n with the Euclidean metric, is also valid on a Kähler manifold.