

The essential step in our construction of  $\Lambda$  is to express the tensor

$$\iota(v)(\Theta) \in A^{0,1}(T' \otimes T'^*)$$

as  $\bar{\theta}$  of a global section of  $T' \otimes T'^*$ . To do this, we recall from Section 5 of Chapter 0 the definition of the torsion associated to a metric on  $T(M)$ .

⌈ See P 77 & P 107

⌋

As we saw then, if  $v_1, \dots, v_n$  is a unitary frame for  $T(M)$ ,  $\varphi_1, \dots, \varphi_n$  the dual coframe for  $T'^*$ ,  $\theta$  the connection matrix of  $D$  in terms of  $\{v_i\}$  and  $\theta^* = -{}^t\theta$  the connection matrix of the dual connection  $D^*$  on  $T'^*$  in terms of  $\{\varphi_i\}$ , then

$$d\varphi_i = \sum \theta_{ij}^* \wedge \varphi_j + \tau_i$$

with  $\tau_i$  of type  $(2,0)$ ; the vector  $\tau = (\tau_1, \dots, \tau_n)$  of 2-forms is called the torsion of the metric in terms of  $\{v_i\}$ .

⌈ According to P 76,  $\theta = -{}^t\theta^* \Rightarrow \theta^* = -{}^t\theta \Rightarrow \theta^* = \bar{\theta}$ .  
See Lemma on P 76.

⌋

Now if

$$\{v_i'\} = \sum g_{ij} \cdot v_j$$

is another frame,  $\{\varphi_i'\}$  the dual coframe, and  $\theta'$ , and  $\theta'^*$  the connection matrices of  $D$  and  $D^*$  in terms of  $\{v_i'\}$  and  $\{\varphi_i'\}$ , then in matrix notation and setting  $g^* = {}^tg^{-1}$

$$\varphi' = g^* \cdot \varphi,$$

$$\theta'^* = g^* \cdot \theta^* \cdot {}^tg + d(g^*) \cdot {}^tg.$$

and